

# 1) ABSTRACT SPACES AND LINEAR OPERATORS

## METRIC SPACES

$$M = (X, d)$$

set  $X$   $\subset$  distance

$d: X \times X \rightarrow \mathbb{R}$  is a distance if

$$(i) \quad d(x, y) = 0 \iff x = y$$

$$(ii) \quad d(x, y) \leq d(x, z) + d(y, z)$$

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$$\Rightarrow (iii) \quad d(x, y) = d(y, x) \quad \left( \text{from (ii) with } x = z \text{ we have } d(z, y) \leq d(y, z) \right)$$

$\Rightarrow$  given the arbitrariness of  $y$  and  $z$   
we must have  $d(y, z) = d(z, y)$

$$\Rightarrow (iv) \quad d(x, y) \geq 0 \quad (\text{from (ii) with } x = y \text{ and (i)})$$

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$M(X, d)$  is a metric space if  $d$  is a distance

Note that  $(X, d_1) \neq (X, d_2)$  if  $d_1 \neq d_2$ !

example  $X = \mathbb{R}^m$   $X = \{x \mid x = (x_1, x_2, \dots, x_m)\} \quad x_i \in \mathbb{R}$

$$d_1(x, y) = \left( \sum_i (x_i - y_i)^2 \right)^{\frac{1}{2}} \quad d_2(x, y) = \max_i |x_i - y_i| \quad M_1 = (X, d_1) \neq M_2 = (X, d_2)$$

NOTE THAT: Physicists call "metric" what is indeed not metric!

$$\text{A vector, } x^{\mu} = (t, \underline{x}) \quad d(x, y) = x^{\mu} x^{\nu} g_{\mu\nu} \quad g_{\mu\nu} = \begin{pmatrix} 1 & & \\ & -1 & \\ & & -1 \end{pmatrix}$$

$$d(x, x') = t^{\mu} - \underline{x} \cdot \underline{x}' \quad d(x, x') = 0 \not\Rightarrow x = x' !!$$

Given a metric space we can extend various concepts seen in Analysis I

$$M = (X, d) \quad \text{"ball" around } x_0 \in X \quad z \in \mathbb{R}^+ \quad B(x_0, r) = \{x \in X \mid d(x, x_0) < r\}$$

OPEN

$$\overline{B}(x_0, r) = \{x \in X \mid d(x, x_0) \leq r\}$$

Neighbourhood :  $B(x_0, \varepsilon)$

A "CLOSED"

- OPEN  $Y \subset X$  is open if  $\forall y \in Y \exists \epsilon > 0 \mid B(y, \epsilon) \subset Y$
- CLOSED  $Y \subset X$  is closed if its complement is open (complement:  $X - Y$ )  
Note that  $Y \subset X$  can be neither closed nor open!

### EXAMPLE

$M = (\mathbb{R}, d)$   $d(x, y) = |x - y|$   $\emptyset$  is open and closed

$[0, 1]$  is closed

$(0, 1)$  is neither open nor closed

$(0, 1)$  is open

- CONVERGENCE  $x_i \in X$   $\lim_{m \rightarrow \infty} x_m = x$  if  $\forall \epsilon > 0 \exists N(\epsilon) \mid m > N \Rightarrow d(x_m, x) < \epsilon$

- CONTINUITY  $T: M_X \rightarrow M_Y$   $M_X = (X, d_1)$   $M_Y = (Y, d_2)$

$T$  is continuous in  $x_0$  if  $\forall \epsilon > 0 \exists \delta(\epsilon) \mid d_1(x, x_0) < \delta \Rightarrow d_2(f(x), f(x_0)) < \epsilon$

- CAUCHY SEQUENCE  $x_i \in X$   $M = (X, d)$

$\{x_i\}$  is a Cauchy sequence if  $\forall \epsilon > 0 \exists N(\epsilon) \mid m, n > N \Rightarrow d(x_m, x_n) < \epsilon$

- COMPLETENESS

$M(X, d)$  is complete if every Cauchy sequence converges in  $M$

### Examples

$$M_1 = (C[0,1], d_1)$$

$C[0,1]$  continuous functions  
over  $[0,1]$

$$M_2 = (C[0,1], d_2)$$

$$d_1 = \max_{t \in [0,1]} |x(t) - y(t)|$$

$$d_2 = \int_a^b |x(t) - y(t)| dt$$

-  $M_1$  is complete. Indeed let's take a Cauchy sequence  $\{x_i\}$

$$\forall \epsilon > 0 \exists N(\epsilon) \mid \max_{t \in [0,1]} |x_N(t) - x_m(t)| < \epsilon$$

$\Rightarrow$  since  $M$  is complete at a given  $x_m(t)$  converges in  $[0,1]$  uniformly to  $x(t)$

Is  $x(t)$  continuous?

Let us write

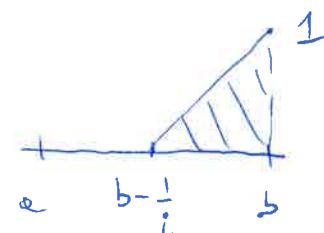
$$|x(t) - x(t_0)| \leq |x(t) - x_m(t)| + |x_m(t) - x_m(t_0)| + |x_m(t_0) - x(t_0)|$$

$$\begin{aligned} \Rightarrow \forall \epsilon > 0 \exists \delta > 0, \exists N(\epsilon) \mid & |x(t) - x_m(t)| < \frac{\epsilon}{3} & \text{because } x_m \text{ converges in } t \\ & |t - t_0| < \delta \\ & m > N(\epsilon) \Rightarrow & |x_m(t) - x_m(t_0)| < \frac{\epsilon}{3} & \text{because } x_n \in C[0,1] \\ & & |x_m(t_0) - x(t_0)| < \frac{\epsilon}{3} & \text{because } x_m \text{ converges in } t_0 \end{aligned}$$

$$\Rightarrow |x(t) - x(t_0)| < \epsilon \Rightarrow x(t) \text{ is continuous and thus belongs to } C[0,1]$$

-  $M_2$  is NOT complete

$$x_i = \begin{cases} 0 & 0 \leq t \leq b - \frac{1}{i} \\ it + 1 - ib & b - \frac{1}{i} \leq t \leq 1 \end{cases}$$



$$d_2(x_m, x_m) \rightarrow 0$$

$$d_2(x_m, x_m) = \int_a^b |x_m(t) - y(t)| dt$$

$$x_i(t) \rightarrow x(t) = \begin{cases} 0 & 0 \leq t < 1 \\ 1 & t = 1 \end{cases}$$

$x(t) \notin C[0,1]$  !

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EXAMPLE

$\mathbb{Q}$  set of rational numbers with  $d(x,y) = |x-y|$  is NOT complete

$$x_0=1 \quad x_1 = \frac{16}{10} \quad x_2 = \frac{161}{100} \quad \dots \quad x_n = \frac{[10^n \sqrt{2}]}{10^n} \rightarrow \sqrt{2} \notin \mathbb{Q} \quad [x] = \text{largest integer in } x$$

$\Rightarrow \mathbb{R}$  is the completion of  $\mathbb{Q}$

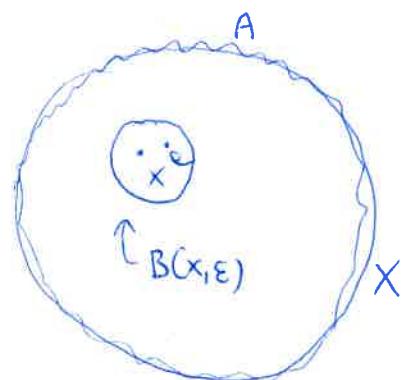
Given  $(X, d)$  not complete metric space, a completion is a pair

$((X', d'), \phi)$  where  $(X', d')$  is a complete metric space and  $\phi$  is an isometry between  $(X, d)$  and  $(X', d')$  |  $\phi(X)$  is dense\* in  $X'$

Isometry = mapping  $\phi : (X, d) \rightarrow (X', d')$  |  $d(x_1, x_2) = d'(\phi x_1, \phi x_2)$

\*  $A \subset X$  is DENSE in  $X$  if  $\forall x \in X$  either  $x \in A$  or every neighbourhood of  $x$  contains at least a point of  $A$ .

Example :  $\mathbb{Q}$  is dense in  $\mathbb{R}$ , because  
every real number can be approximated  
as well as we want by a rational number

THEOREM (without proof)

Given  $(X, d)$  not complete metric space, a completion always exists,  
and it is UNIQUE (up to isometries)

## BANACH SPACES

Up to now we have considered  $X$  as an arbitrary set: from now on

$X$  is a VECTOR SPACE on a field  $\mathbb{K}$  ( $\mathbb{K} = \mathbb{R}$  or  $\mathbb{C}$ )

We define a NORM as a mapping  $\|\cdot\| : X \rightarrow \mathbb{R}$  (also if  $\mathbb{K} = \mathbb{C}$ )

that fulfills the following properties:

$$(i) \quad \|\underline{e}y\| = |\underline{e}| \|y\| \quad y \in X \quad \underline{e} \in \mathbb{K}$$

$$(ii) \quad \|\underline{u} + \underline{v}\| \leq \|\underline{u}\| + \|\underline{v}\|$$

$$(iii) \quad \|\underline{u}\| = 0 \Rightarrow \underline{u} = \underline{0}$$

$$\begin{aligned} (iv) \quad \|\underline{0}\| &= 0 \quad (\text{because } \underline{0} = \underline{0} \underline{0} \text{ and } |\underline{0}| = 0 \Rightarrow (iii) \text{ also holds}) \\ &\quad \text{in the opposite sum} \\ (v) \quad \|\underline{u}\| &\geq 0 \quad (0 = \|\underline{u} - \underline{u}\| \leq \|\underline{u}\| + \|\underline{u} - \underline{u}\| = 2\|\underline{u}\|) \end{aligned}$$

Every norm induces a METRIC  $d(x, y) = \|x - y\|$

### PROOF

$$(i) \quad d(\underline{x}, \underline{y}) = 0 \Leftrightarrow \underline{x} = \underline{y}$$

$$\underline{x} = \underline{y} \Rightarrow d(\underline{x}, \underline{y}) = \|\underline{0}\| = 0$$

$$d(\underline{x}, \underline{y}) = 0 \Rightarrow \|\underline{x} - \underline{y}\| = 0 \Rightarrow \underline{x} = \underline{y}$$

(ii)

$$d(\underline{x}, \underline{z}) = \|\underline{x} - \underline{z}\| = \|\underline{x} - \underline{z} + \underline{z} - \underline{y}\| \leq \|\underline{x} - \underline{z}\| + \|\underline{z} - \underline{y}\| = d(\underline{x}, \underline{z}) + d(\underline{z}, \underline{y})$$

$\Rightarrow$

EVERY NORMED SPACE IS A METRIC SPACE, WITH THE METRIC  
INDUCED BY THE NORM

5)

A Banach space is a normed vector space which is complete with respect to the metric induced by the norm.

example

$C[0,1]$  continuous functions over  $[0,1]$        $x(t) \in C[0,1]$

1)  $\|x\| = \max_{t \in [0,1]} |x(t)| \rightarrow$  complete  $\rightarrow$  Banach space! (see previous example)

2)  $\|x\| = \int_0^1 |x(t)| dt \rightarrow$  not complete  $\rightarrow$  it is not Banach space!

### 3) LINEAR OPERATIONS

$T: (X, \|\cdot\|_X) \rightarrow (Y, \|\cdot\|_Y)$        $X, Y$  normed vector spaces over the same field ( $\mathbb{R}$  or  $\mathbb{C}$ )

$$x_1, x_2 \in X \quad T(\alpha x_1 + \beta x_2) = \alpha T(x_1) + \beta T(x_2)$$

$D_T$  domain     $\{x \in X \mid Tx \text{ is defined}\}$

$R_T$  range     $\{y \in Y \mid y = Tx\}$

$N_T$  kernel     $\{x \in X \mid Tx = 0\}$        $\underbrace{\text{null element in } Y}$

example

$T: (C[0,1], \|\cdot\|) \rightarrow (\mathbb{K}, \|\cdot\|)$

linear functionals  
(e.g. calculus of variations)

$\rightarrow$  space of test functions

$T: (C_c^\infty(\mathbb{R}^n), \|\cdot\|) \rightarrow (\mathbb{K}, \|\cdot\|)$

DISTRIBUTIONS

$C_c^\infty(\mathbb{R}^n)$  class  $C^\infty$  functions with compact support

$T: X \rightarrow Y$      $X, Y$  normed spaces     $T$  linear

def:  $T$  is BOUNDED if  $\exists c \in \mathbb{R}$  |  $\|Tx\| \leq c\|x\| \quad \forall x \in D_T$

$$\text{If this is the case the minimum } c \Rightarrow \sup_{\substack{x \in D_T \\ x \neq 0}} \frac{\|Tx\|}{\|x\|} = \sup_{\substack{x \in D_T \\ \|x\|=1}} \|Tx\| \equiv \|T\|$$

$$\Rightarrow \|Tx\| \leq \|T\| \|x\|$$

this step is due to  
the linearity!

### THEOREM

(set  $x = \|x\|y$   
 $\Rightarrow \|x\|$  cancels in the ratio)

Let  $X, Y$  be normed vector spaces and let

$T: X \rightarrow Y$  a linear operator

The following statements are equivalent

(i)  $T$  is bounded

(ii)  $T$  is continuous on  $X$

(iii)  $T$  is continuous in  $x_0 \in X$

### Proof

let us choose  $x_0 \in X$  and  $\epsilon > 0 \Rightarrow$  choose  $\delta = \epsilon / \|T\|$

(ii)  $\Rightarrow$  (iii)

$\forall x \mid \|x - x_0\| < \delta \quad \text{we have} \quad \|Tx - Tx_0\| = \|T(x - x_0)\| \leq \|T\| \|x - x_0\| < \epsilon$

$\Rightarrow T$  is continuous

(ii)  $\Rightarrow$  (i) trivial

(iii)  $\Rightarrow$  (ii) Suppose  $T$  is continuous in  $x_0 \Rightarrow \forall \epsilon > 0 \exists \delta > 0 \mid \|x - x_0\| < \delta \Rightarrow \|Tx - Tx_0\| < \epsilon$

Choose  $y \neq 0$  in  $D_T$  and set  $x = x_0 + \frac{\delta}{\|y\|} y \Rightarrow x - x_0 = \frac{\delta}{\|y\|} y$

$$\Rightarrow \|Tx - Tx_0\| = \|T(x - x_0)\| = \|T \frac{\delta}{\|y\|} y\| = \frac{\delta}{\|y\|} \|Ty\| < \epsilon \Rightarrow \|Ty\| < \frac{\epsilon}{\delta} \|y\|$$

BOUNDED! □

## HILBERT SPACES

We consider a vector space  $X$  over field  $k$  ( $= \mathbb{R}$  or  $\mathbb{C}$ )

$$x, y, z \in X \quad \alpha, \beta \in k$$

We define a scalar product (inner product) on  $X$  as a mapping from  $X \times X \rightarrow k$

with the following properties:

$$(i) \langle x | \alpha y + \beta z \rangle = \alpha \langle x | y \rangle + \beta \langle x | z \rangle$$

$$\langle x, y \rangle \in k$$

$$(ii) \langle x | y \rangle = \langle y | x \rangle^*$$

$$\langle x, y \rangle \text{ DIRECT NOTATION}$$

$$(iii) \langle x | x \rangle \geq 0 \quad \text{and} \quad \langle x | x \rangle = 0 \iff x = 0$$

NOTE: Sometimes the linearity is important on the first argument!

NOTE: With this definition the scalar product is  
ANTI-LINEAR on the first argument

$$\langle \alpha x | y \rangle = \langle y | (\alpha x) \rangle^* = \alpha^* \langle x | y \rangle$$

NOTE: If  $k = \mathbb{R} \Rightarrow \langle x | y \rangle = \langle y | x \rangle$

Given the definition of scalar product  $\Rightarrow$  a NORM is induced as  $\|x\| = \sqrt{\langle x | x \rangle}$

Let us check that this is indeed a norm

$$\|ex\|^2 = \langle ex | ex \rangle = |\alpha|^2 \|x\|^2 \quad \text{OK}$$

$$\|x+y\|^2 = \langle x+y | x+y \rangle = \|x\|^2 + \|y\|^2 + \langle x | y \rangle + \langle y | x \rangle$$

$$= \|x\|^2 + \|y\|^2 + 2 \operatorname{Re} \langle x | y \rangle$$

$$\leq \|x\|^2 + \|y\|^2 + 2 |\langle x | y \rangle|$$

$$\leq \|x\|^2 + \|y\|^2 + 2 \|x\| \|y\| = (\|x\| + \|y\|)^2 \quad \text{OK}$$

↑ THIS LAST STEP IS DUE TO THE CAUCHY-SCHWARTZ INEQUALITY (to be proved later)

$$\|x\| = \langle x | x \rangle = 0 \Rightarrow x = 0 \quad \text{OK}$$

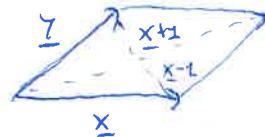
8) A vector space with a scalar product is also called as PRE-HILBERT SPACE

Since the scalar product induces a norm, and the norm induces a METRIC, we can establish if the space is COMPLETE

⇒ A HILBERT SPACE IS A VECTOR SPACE WITH SCALAR PRODUCT WHICH IS COMPLETE WITH RESPECT TO THE METRIC INDUCED BY THE NORM

• Parallelogram equality

$$\|x+y\|^2 + \|x-y\|^2 = 2\|x\|^2 + 2\|y\|^2$$



⇒ If a normed vector space does not respect this rule it cannot be a Hilbert space!

• Cauchy-Schwarz inequality

$$|\langle x|y \rangle| \leq \|x\| \|y\|$$

$x=0$  or  $y=0$  obvious

⇒  $x \neq 0, y \neq 0$

$$x = \frac{\langle y|x \rangle}{\|y\|^2} y + z$$

$$\langle y|x \rangle \pm \langle y|x \rangle + \langle y|z \rangle$$

$$\Rightarrow \langle y|z \rangle = 0$$

$$\Rightarrow \|x\|^2 = \frac{|\langle y|x \rangle|^2}{\|y\|^4} \|y\|^2 + \|z\|^2 \geq \frac{|\langle y|x \rangle|^2}{\|y\|^2}$$

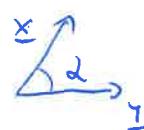
Example

$$X = \mathbb{R}^2$$

$$|\langle x|y \rangle| = |x_1 y_1 + x_2 y_2| = \|x\| \|y\| |\cos \varphi|$$

$$= (x_1, x_2)$$

$$\leq \|x\| \|y\|$$



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EXAMPLE

$$\mathbb{C}^m \quad x = (x_1 \dots x_m) \quad x_i \in \mathbb{C}$$

$$\langle x | y \rangle = \sum_{i=1}^m x_i^* y_i \quad \text{is a Hilbert space}$$

(i), (ii) and (iii) easily checked

EXAMPLE

$$\ell^2 \quad x = (x_1, \dots) \quad \text{such that} \quad \sum_{i=1}^{\infty} |x_i|^2 < \infty$$

$$\langle x | y \rangle = \sum_{i=1}^{\infty} x_i^* y_i \quad \|x\| = \sqrt{\sum_{i=1}^{\infty} |x_i|^2}$$

C note that the sum converges (follows from CS inequality at finite n)

EXAMPLE

$\mathbb{C}[0,1]$  we have already considered this space as a normed space; is it a HS?

- $\|x\|_1 = \max_{t \in [0,1]} |x(t)|$  we have already seen that this is a Banach space

but  $\|x\|_1$  does not fulfill the parallelogram rule

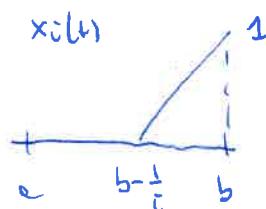
$\Rightarrow$  it does not come from a scalar product  $\Rightarrow$  NOT A HS

- $\|x\|_2 = \left[ \int_a^b |x(t)|^2 dt \right]^{1/2}$  this comes from a scalar product  
 $\Rightarrow$  it fulfills the Parallelogram rule

$$\langle x | y \rangle = \int_a^b dt \quad x^*(t) y(t)$$

However  $\mathbb{C}[0,1]$  with this norm is NOT complete

$\Rightarrow$  THIS IS NOT A HS (pre-Hilbert space)



$x_i$  are Cauchy sequence but  $x_i \rightarrow x$

$$\begin{cases} x(t) = 0 & a \leq t < b \\ x(t) = 1 & t = b \end{cases}$$

$x(t) \notin \mathbb{C}[0,1]$

EXAMPLE $L^2[a,b]$ functions defined over  $[a,b]$ that are square-integrable according to Lebesgue

$$\int_a^b dt |x(t)|^2 < \infty$$

$\uparrow$  not necessarily continuous!

L: Lebesgue integral (generalization of Riemann integral)

The elements of  $L^2[a,b]$  are Equivalence Classes of functions

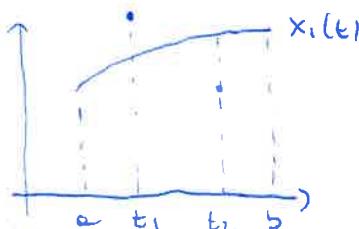
Recall: Equivalence relation in an arbitrary set  $X$ : collection of ordered pairs  $R$  of  $X$  of the kind  $(a,b)$  with  $a,b \in X$ . If  $(a,b) \in R$  we say that  $a \sim b$ . To be called equivalence relation it must fulfill:

- $a \sim a$  (reflexivity)
- $a \sim b \Rightarrow b \sim a$  (symmetry)
- $a \sim b$  and  $b \sim c \Rightarrow a \sim c$  (transitivity)

An equivalence relation allows us to split the set into classes.

$x(t) \sim y(t)$  if  $x(t) = y(t)$  almost everywhere

more precisely: except a set with vanishing integral



$$x_2(t) = x_1(t) \quad t \neq t_1$$

$$x_1 \sim x_2 \quad x_1 \sim x_3$$

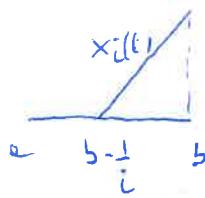
$$x_3(t) = x_1(t) \quad t \neq t_2$$

If  $x_4(t) = x_1(t)$  everywhere except  $t_3 < t < t_4 \Rightarrow x_1 \not\sim x_4$

If  $x_1(t) \sim 0 \Rightarrow x_1(t) = 0$  almost everywhere  $\Rightarrow \int_a^b x_1(t) dt = 0$

$L^2[a,b]$  with the scalar product  $\langle x|y \rangle = \int_a^b x^*(t)y(t) dt$  it is complete  $\Rightarrow$  HS!

Going back to our previous example



$$x_i \rightarrow 0 \quad \text{in } L^2[a,b]$$

$L^2[a,b]$   
wave functions  
in quantum  
mechanics!

$B(X, Y)$  space of all the bounded linear operators from  $M_X = (X, \|\cdot\|_X) \rightarrow M_Y = (Y, \|\cdot\|_Y)$

it is itself a normed space  $T_i \in B(X, Y)$

$$T_1 + T_2, \quad dT, \quad \|T\|$$

$\curvearrowleft$  it exists because the operators are bounded

We can consider as a special case the case  $Y = \mathbb{R}$  or  $\mathbb{C}$  (with the standard metric)

$B(X, k)$  ( $k = \mathbb{R}$  or  $\mathbb{C}$ ) is thus the space of linear continuous (bounded) functionals on  $X$

DEF  $M(X, \|\cdot\|)$  normed space  $\tilde{M}$  DUAL SPACE:

space of all the continuous linear functionals  $\tilde{M} = B(X, \mathbb{K})$

$\Rightarrow$  IT IS A BANACH SPACE (regardless on whether  $M$  is BS or not!)

### LINEAR OPERATORS ON HILBERT SPACES

notation  $|X\rangle \in H$  "Ket"       $\langle X| \in \tilde{H}$  "Bra"

scalar product  $\langle Y | X \rangle$

$\langle X | \in \tilde{H}$  is defined with this notation because of the RIESZ REPRESENTATION THEOREM:

Every element of  $\tilde{H}$  (continuous function  $f: H \rightarrow K$ ) can be uniquely represented by  $f(x) = \langle y | x \rangle$   $y \in H$

We start by considering the case  $\dim H < \omega$

$\Rightarrow$  linear operators become essentially MATRICES  $\Rightarrow$

we can use the standard framework of linear algebra

$$\{|q_i\rangle\}_{i=1 \dots N}$$

orthonormal basis

$$\langle q_i | q_j \rangle = \delta_{ij}$$

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$$\|x\| = \sum_{i=1}^m |\varphi_i(x)|$$

$$|x\rangle = \|x\| |x\rangle = \sum_{i=1}^m |\varphi_i(x)| |x\rangle = \sum_i c_i |\varphi_i\rangle$$

$$H \sim \mathbb{K}^m$$

$$|x\rangle \sim (c_1 \dots c_m)$$

↑  
expansion  
coefficient

$$\begin{aligned} T|x\rangle &= T \sum_{j=1}^n c_j |\varphi_j\rangle = \sum_{j=1}^n c_j (T|\varphi_j\rangle) & T\varphi_j &= \sum_i T_{ij} |\varphi_i\rangle \\ && b \in H & \\ &= \sum_{i,j=1}^n c_j T_{ij} |\varphi_i\rangle \end{aligned}$$

$\Rightarrow$  WE CAN SHOW THAT ALL LINEAR OPERATIONS ON  $H$ ,  $\dim H < \infty$  ARE BOUNDED (CONTINUOUS)

$$\left\{ \|Tx\|, \|x\|=1 \right\} = \left\| \sum_{i,j=1}^n c_j T_{ij} |\varphi_i\rangle \right\| \leq \sum_i |c_j| |T_{ij}| \leq \sum_i |T_{ij}|$$

### GRAM-SCHMIDT procedure

Given  $m$  linearly independent vectors  $\{\underline{v}_i\}$  we can construct an orthonormal basis

$$\left\{ \begin{array}{l} \underline{u}_1 = \underline{v}_1 \\ \underline{u}_2 = \underline{v}_2 - \frac{\langle \underline{v}_2 | \underline{u}_1 \rangle}{\|\underline{u}_1\|^2} \underline{u}_1 \\ \underline{u}_3 = \underline{v}_3 - \frac{\langle \underline{v}_3 | \underline{u}_1 \rangle}{\|\underline{u}_1\|^2} \underline{u}_1 - \frac{\langle \underline{v}_3 | \underline{u}_2 \rangle}{\|\underline{u}_2\|^2} \underline{u}_2 \\ \vdots \end{array} \right.$$

$\underline{e}_i = \frac{\underline{u}_i}{\|\underline{u}_i\|}$   
 $\underline{u}_2 = \underline{v}_2 - d \underline{u}_1$   
 $\langle \underline{v}_2 | \underline{u}_1 \rangle = \langle \underline{v}_2 | \underline{u}_2 \rangle = 0$   
 $-d \|\underline{u}_1\|^2 = 0$   
 $\Rightarrow d = \frac{\langle \underline{v}_2 | \underline{u}_1 \rangle}{\|\underline{u}_1\|^2}$

Roughly speaking : subtract from the  $m$  vector its projection onto  
the previous  $M-1$  vectors

- EIGENVALUES AND EIGENVECTORS

If  $\exists |x\rangle \neq 0$  and  $T|x\rangle = \lambda|x\rangle$

$|x\rangle$  eigenvector of  $T$  with eigenvalue  $\lambda$

- RESOLVENT OPERATOR

If  $R_T(\lambda) = (T - \lambda I)^{-1}$  exists, it is called RESOLVENT

If  $R_T(\lambda)$  exists  $\Rightarrow \lambda$  is not an eigenvalue!

- SYMMETRIC OPERATORS

$T$  linear operator on  $H$  is symmetric if  $\forall x, y \in D_T \quad \langle Tx|y\rangle = \langle x|Ty\rangle$

- ADJOINT

$T$  bounded operator on  $H \Rightarrow \exists T^+ \mid \forall x, y \in H \quad \langle y|Tx\rangle = \langle T^+y|x\rangle$

Indeed let us fix  $y \in H$  and define  $Lx = \langle y|Tx\rangle$

$\Rightarrow L$  is a bounded linear functional on  $H \Rightarrow$  according to the Riesz theorem  $\exists ! h \in H \mid Lx = \langle h|x\rangle$

Defining  $h = T^+y$  we have  $\langle y|Tx\rangle = \langle T^+y|x\rangle$

One can show that  $T^+$  is also linear and bounded

- HERMITIAN OPERATORS

A linear operator  $T$  on  $H$  is Hermitian (self-adjoint) if  $T = T^+$

In the case in which  $\dim H < \infty$  Symmetric  $\Leftrightarrow$  Hermitian

Indeed for linear  $T$  we have

$$\langle \varphi_i | T \varphi_j \rangle = T_{ij} = \langle T^+ \varphi_i | \varphi_j \rangle = \langle \varphi_j | T^+ \varphi_i \rangle^* = (T^+)^*_{ji}$$

13/ If  $T$  is symmetric we have

$$\langle \varphi_i | T \varphi_j \rangle = \langle T \varphi_i | \varphi_j \rangle \Rightarrow T_{ij} = T_{ji}^* \Rightarrow T = T^*$$

If  $T = T^*$  the eigenvalues of  $T$  are real. Indeed suppose  $T|u\rangle = \lambda|u\rangle$

$$\Rightarrow \langle u | Tu \rangle = \lambda \|u\|^2 = \langle T^* u | u \rangle = \langle Tu | u \rangle = \langle u | Tu \rangle^* \Rightarrow \lambda = \lambda^*$$

We can choose an orthonormal set  $\{|x_i\rangle\}$  such that  $T|x_i\rangle = \lambda_i|x_i\rangle$

$$T|x\rangle = T \cdot \mathbb{1}|x\rangle = T \sum_{i=1}^m |x_i\rangle \langle x_i | x \rangle = \sum_i \lambda_i \langle x_i | x \rangle |x_i\rangle$$
$$= \sum_i \lambda_i P_i|x\rangle$$

$$P_i = |x_i\rangle \langle x_i| \text{ if } x_i \text{ has multiplicity 1}$$

$$P_i = \sum_{e=1}^{m_i} |x_{ei}\rangle \langle x_{ei}| \text{ if } m_i > 1$$

The projectors are idempotent:  $P_j^2 = P_j$  and  $P_j P_e = 0$  if  $j \neq e$

Moreover (still  $\dim H < \infty$ ) we can decompose  $H$  as

$$H = H_1 \oplus H_2 \oplus \dots \oplus H_m \quad \leftarrow \text{direct sum}$$

HOW TO EXTEND THIS  
TO ARBITRARY HILBERT  
SPACES?

### ORTHOGONAL COMPLEMENT

We now move to consider the case in which  $\dim H$  is arbitrary

$H$  Hilbert space  $\gamma \subset H$  subspace ( $y_1, y_2 \in \gamma \quad \lambda y_1 + \beta y_2 \in \gamma$ )

If  $\gamma$  is closed  $\Rightarrow \gamma$  is complete  $\Rightarrow \gamma$  is also a Hilbert space

Indeed let us consider  $x_n \in \gamma$  of Cauchy type  $\Rightarrow x_n \rightarrow x \in H$  since

$H$  is complete. But since  $\gamma$  is closed then  $x \in \gamma$

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### EXAMPLE

$H = L^2[0,1]$      $Y = C[0,1]$      $Y \subset H$  and subspace but it is not complete!  
 $\Rightarrow$  it is not Hilbert space!

Consider a closed subspace  $Y \subset H \Rightarrow$  the orthogonal complement  $Y^\perp$

is defined as  $Y^\perp = \{z \in H \mid z \perp y \ \forall y \in Y\}$

Note that  $Y \cap Y^\perp = \{0\}$

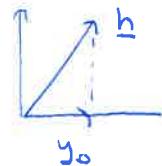
### DIRECT SUM

We say that  $H = Y \oplus Z$  if  $\forall x \in H \exists! y \in Y$  and  $z \in Z \mid x = y + z$

### PROJECTION THEOREM

$H$  Hilbert space,  $Y$  closed subspace  $\Rightarrow \forall h \in H \exists! y \in Y \mid h - y \perp z \ \forall z \in Y$

$y_0$  is said to be the projection of  $h$  on  $Y$



### PROOF

We start by showing that if  $y_0$  exists, then it is unique.

Let  $y_1$  and  $y_2$  two projections of  $h \Rightarrow \forall y \in Y \quad \langle h - y_1 | y \rangle = 0$

and  $\langle h - y_2 | y \rangle = 0 \Rightarrow \langle y_1 - y_2 | y \rangle = 0$  but since  $y$  is arbitrary, set  $y = y_1 - y_2$

$\Rightarrow \|y_1 - y_2\| = 0 \Rightarrow y_1 = y_2$ .

We now have to prove the existence of the projection. Consider

$d = \inf \{ \|h - y\|, y \in Y\}$  and define a sequence  $y_m \in Y$  such that

$$d \leq \|h - y_m\| < d + \frac{1}{m}$$

 By using the parallelogram rule we can show that  $y_m$  is a Cauchy sequence

$$\|y_m - y_{m+1}\|^2 = \left\| \begin{smallmatrix} x \\ y \end{smallmatrix} + (h - \begin{smallmatrix} x \\ y \end{smallmatrix}) \right\|^2 = 2 \left( \|y_m - h\|^2 + \|h - y_{m+1}\|^2 \right)$$

$$-\left\| \begin{smallmatrix} x \\ y \end{smallmatrix} - (h - \begin{smallmatrix} x \\ y \end{smallmatrix}) \right\|^2 = 2 \left( \|y_m - h\|^2 + \|h - y_{m+1}\|^2 \right) - 4 \left\| \frac{\begin{smallmatrix} x \\ y \end{smallmatrix} + (h - \begin{smallmatrix} x \\ y \end{smallmatrix})}{2} - h \right\|^2 \leq d^2$$

Now given  $\epsilon > 0 \exists N(\epsilon) \mid \|y_m - h\|^2 < d^2 + \frac{\epsilon}{4} \text{ if } m > N(\epsilon)$

and  $\|y_m - h\|^2 < d^2 + \frac{\epsilon}{4} \text{ if } m > N(\epsilon)$

$$\Rightarrow \|y_m - y_{m+1}\|^2 \leq 2 \left( 2d^2 + \frac{\epsilon}{2} \right) - 4d^2 = \epsilon \Rightarrow y_m \text{ is of Cauchy type.}$$

Since the Hilbert space is complete  $y_m$  converges : let  $y_0 = \lim_{m \rightarrow \infty} y_m$

We have  $d = \lim_{m \rightarrow \infty} \|h - y_m\| = \|h - y_0\| \Rightarrow \|h - y_0\| \leq \|h - y\| \forall y \in Y$

This is enough to show that  $y_0$  is the projection. Indeed

$$\|h - y_0 + ty\|^2 = \|h - y_0\|^2 + t^2\|y\|^2 + 2t \operatorname{Re} \langle h - y_0, y \rangle \quad y \text{ arbitrary}$$

$t \text{ real}$

But  $\|h - y_0 + ty\|^2 - \|h - y_0\|^2$  must always be positive and minimum for  $t=0$

Since  $\|h - y_0 + ty\|^2 - \|h - y_0\|^2$  is a polynomial in  $t$ , the linear term has to vanish  $\Rightarrow \operatorname{Re} \langle h - y_0, y \rangle = 0$

But  $y$  was arbitrary, so we could choose  $y \rightarrow iy \Rightarrow \langle h - y_0, y \rangle = 0$

$\Rightarrow$  We conclude that  $y_0$  is the projection of  $h$  on  $Y$  and it is unique ■

Given  $h \in H$  and  $Y \subset H$  closed subspace, we can always write  $h = y + z$  with  $y \in Y$  and  $z \in Y^\perp$

ORTHONORMAL BASIS

When  $\dim H = m$  we can find an orthonormal basis by looking for a set of  $m$  linearly independent vectors and applying the Gram-Schmidt procedure.

How can we do this when  $\dim H = \infty$ ?

$\{|\varphi_i\rangle\}$  orthonormal system

$$\text{span of } \{|\varphi_i\rangle\} \equiv \{x \mid x = \sum_{i=1}^m \lambda_i |\varphi_i\rangle, m \in \mathbb{N}\}$$

DEF  $\{|\varphi_i\rangle\}$  is complete if  $\text{span of } \{|\varphi_i\rangle\}$  is dense in  $H$

(alternatively:

$$(y \in \text{span of } \{|\varphi_i\rangle\}^\perp \Rightarrow y=0)$$

↓ It means that every element of  $H$  can be approximated as well as we like with an element of  $\text{span of } \{|\varphi_i\rangle\}$

PROJECTORS

$$P : H \rightarrow Y \quad | \quad Px = y$$

T projection

$H$  Hilbert space

$Y$  closed subspace

$$P^2 = P \quad \text{and} \quad \|P\| = 1$$

## Separable HS

A Hilbert space is said to be separable if it has a complete orthonormal basis

$$\{|\varphi_i\rangle\}_{i=1,2,\dots}$$

Relevant HS are all separable: They are also the natural extension of HS of finite dimension!

$$|\gamma\rangle = \sum_{i=1}^{\infty} y_i |\varphi_i\rangle$$

(more precisely it means

$$|\gamma_N\rangle = \sum_{i=1}^N y_i |\varphi_i\rangle$$

$$\lim_{N \rightarrow \infty} |\gamma_N\rangle = |\gamma\rangle \quad (\Rightarrow \lim_{N \rightarrow \infty} \|y_N\| = 0)$$

example :  $L^2[-1,1]$

$$|M_i\rangle = t^i \quad -1 \leq t \leq 1$$

span  $\{|M_i\rangle\}$  is the set of polynomials on  $[-1,1]$

span  $\{|M_i\rangle\}$  is dense in  $C[-1,1]$ , but  $C[-1,1]$  is dense in  $L^2[-1,1]$

Using the Gram-Schmidt construction we can construct the LEGENDRE POLYNOMIALS

$$P_0(x) = 1$$

$$P_1(x) = x$$

$$P_2(x) = \frac{1}{2}(3x^2 - 1) \quad \dots$$

$$P_m(x) = \frac{1}{2^m m!} \frac{d^m}{dx^m} (x^2 - 1)^m$$

example

$$L^2(-\infty, \infty)$$

$$|M_0\rangle = e^{-t^2/2}$$

$$|M_i\rangle = t |M_{i-1}\rangle$$

$$h_0(x) = 1$$

$$h_1(x) = 2x$$

$$h_2(x) = 4x^2 - 2$$

example

$$L^2[0, \infty)$$

$$|M_0\rangle = e^{-t^2/2}$$

$$|M_i\rangle = t |M_{i-1}\rangle$$

BY

Gram-Schmidt  $\rightarrow$  Legendre

- $\ell^2 \quad x \in \ell^2 \quad x = (x_1, x_2, \dots, x_n, \dots) \quad \sum |x_i|^2 < \infty \quad x_i \in \mathbb{C}$

- $|\varphi_i\rangle \sim (0, \dots, 1, 0, \dots)$  Complete orthonormal system

$\tau_i$  preserving

SEPARABLE  
All dim =  $\infty$  HS are  
ISOMORPHIC TO  $\ell^2$

example

$$H = L^2[-\pi, \pi]$$

$$|\psi_k\rangle = \frac{1}{\sqrt{2\pi}} e^{ikt}, k \in \mathbb{Z} \quad \text{is an orthonormal basis}$$

at

We know that any continuous function in  $[-\pi, \pi]$  with continuous derivative can be expanded in Fourier series. But these functions form a dense set in  $L^2[-\pi, \pi]$   
 $\Rightarrow \{|\psi_k\rangle\}$  is a complete basis.

example: non-separable space

$$t \mapsto e^{ist} \quad t \in \mathbb{R} \quad s \text{ real parameter}$$

We consider the linear span of these functions with the product  $\langle f | g \rangle = \lim_{T \rightarrow \infty} \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t) \overline{g(t)} dt$   
 we have just taken  $f(t) = e^{ist} \quad g(t) = e^{irt} \quad r \neq s$

$$\langle f | g \rangle = \lim_{T \rightarrow \infty} \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{i(s-r)t} dt = 0 \quad \|g\| = 1$$

$\Rightarrow$  These functions provide a non numerable basis for the H.S.  $\Rightarrow$  NON SEPARABLE

- CLOSED, BOUNDED, COMPACT OPERATORS

Up to now we have considered, in the class of linear operators, those that are BOUNDED.

We have seen that if  $\dim H$  is finite  $\Rightarrow$  all linear operators are indeed bounded.

However in Physics not all important operators are BOUNDED!

example

$$\psi(x) \in L^2[0,1]$$

$$P = -i\hbar \frac{\partial}{\partial x} \quad \begin{matrix} \text{momentum} \\ * \\ \text{operator} \end{matrix}$$

$$|\psi_m\rangle \sim \psi_m(x) = x^m \quad \|\psi_m\|^2 = \int_0^1 x^{2m} dx = \frac{1}{2m+1}$$

$$\|\psi_m\| \rightarrow 0$$

$$P(\psi_m) \sim m x^{m-1}$$

$$\Rightarrow \|P\psi_m\| = \frac{m}{\sqrt{2m-1}}$$

and there is no constant C

$$\|P\psi_m\| \leq C \|\psi_m\|$$

However the important operators in physics are CLOSED

2)

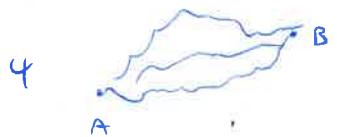
## WAVE OPTICS

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## GEOMETRIC OPTICS

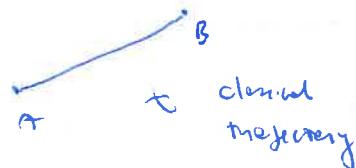
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## WAVE MECHANICS



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$$\sum_{\text{paths}} e^{i \frac{S}{\hbar}}$$



$$\hat{P} = \alpha \frac{\partial}{\partial x}$$

$$\Psi_{cl} = e^{i \frac{S}{\hbar}}$$

$$\hat{P}\Psi_{cl} = \alpha \frac{i}{\hbar} \frac{\partial S}{\partial x} \Psi_{cl}$$

$$\Rightarrow \text{but classical momentum} \Rightarrow \underline{P} = \nabla S^* \Rightarrow \alpha = -i\hbar$$

$$1) \text{ Translation operator } S\Psi = \frac{\partial \Psi}{\partial z} S_1 \quad T \sim \nabla$$

Inverse under translation  $\Rightarrow$  conservation of momentum  $\Rightarrow \underline{P}$  must be  $\sim \nabla$

$$(x) \quad SS = \frac{\partial L}{\partial \dot{x}} \delta x \Big|_{t_1}^{t_2} + \int_{t_1}^t \left( \frac{\partial L}{\partial \dot{x}^*} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} \right) \delta x^* dt$$

$\Rightarrow$  consider physical quantities that fulfill the Euler equations

but subtract  $\delta x(t_1) = 0$  and  $\delta x(t_2) = \delta x$  is arbitrary

$$\Rightarrow \frac{\partial S}{\partial x} = P = \frac{\partial L}{\partial \dot{x}}$$

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## CLOSED OPERATORS

DEF

Let us consider an operator  $T: D_T \subset H \rightarrow H$  linear.  $T$  is closed if

$\forall x_n \in D_T$  with  $x_n \rightarrow x \in H$  and  $Tx_n \rightarrow y$  we have  $x \in D_T$  and  $y = Tx$

Note that BOUNDED  $\not\Rightarrow$  closed

## EXAMPLE

$H = \mathbb{R}$ ,  $D_T = \mathbb{Q} \subset \mathbb{R}$        $Tx = x$        $T$  is bounded ( $\|T\| = 1$ )      but not closed

$$x_m = \left(1 + \frac{1}{n}\right)^m \in D_T \quad x_m \rightarrow x (= e) \quad Tx_m \rightarrow y (= e) \quad \text{but } x \notin D_T$$

A linear bounded operator is closed if  $D_T$  is a closed set.

## COMPACT OPERATORS

We know that if  $X$  is a normed space and  $\dim X < \infty \Rightarrow$  the Bolzano-Weierstrass theorem holds,

$\forall x_m \in X$ ,  $x_m$  bounded  $\exists x_{m_n}$  subsequence of  $x_m$   
which is convergent

However this does not hold if  $\dim X = \infty$ !

## EXAMPLE

$$X = \mathbb{R}^n \quad S = \left\{ x \in X \mid \sum_{i=1}^n x_i^2 = 1 \right\} \quad \text{sphere in } \mathbb{R}^n$$

given  $x^{(i)} = (x_1^{(i)}, x_2^{(i)}, \dots, x_n^{(i)})$  sequence with  $i = 1, 2, \dots, \infty$

$\exists$  convergent subsequence (points have to accumulate somewhere!)

take now  $n = \infty$  and consider

$$x^{(i)} = (0, 0 \dots 1, 0 \dots 0 \dots) \quad x^{(i)} \in S^\infty \quad \text{bounded sequence}$$

$\curvearrowleft$  i position

$\nexists$  convergent subsequence! (points "spread" across the infinite dimensions)

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This result motivates us to give the following definition:

DEF  $X$  normed linear space,  $A \subset X$  is RELATIVELY COMPACT

if  $\forall x_n \in A \exists x_m$  subsequence which is CONVERGENT

A relatively compact set  $A$  is bounded. In fact, suppose it is not.

Then there must be a sequence  $x_n \in A$  |  $\lim_{n \rightarrow \infty} \|x_n\| = \infty$ . But

such a sequence would not have a convergent subsequence.

A subset  $A \subset X$  is COMPACT if it is RELATIVELY COMPACT and CLOSED

We can now define a COMPACT OPERATOR

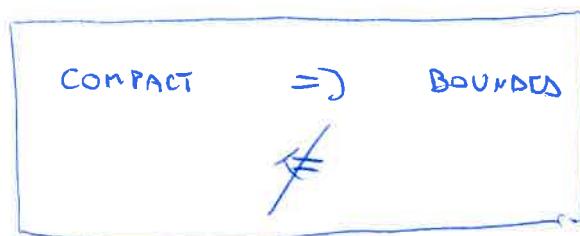
T BOUNDED : bounded set  $M \xrightarrow{T}$  bounded set  $M'$

DEF T compact : bounded set  $M \xrightarrow{T}$  relatively compact set  $M'$

A compact operator is bounded, since a relatively compact set is bounded

A bounded operator is not necessarily compact

(e.g. the identity operator  
is bounded but  
not compact)



e.g. momentum operator is  
not bounded  $\Rightarrow$  not compact!

EXAMPLE

$$T_N : \ell^2 \rightarrow \ell^2 \quad x = (x_1, x_2, \dots) \quad T_N x = (x_1, x_2, \dots, x_N, 0, 0, \dots)$$

$T_N$  is compact. Indeed its range is  $\ell^N$  and it is finite dimensional

$\Rightarrow$  a bounded set is sent into a relatively compact set for the Bolzano-Weierstrass theorem.

13)

EXAMPLE

The identity operator in  $\ell^2 \rightarrow \ell^2$  is not compact.

Consider  $x_n = (0, 0, \dots, 1, 0, 0, \dots)$        $x_m$  is bounded  
 $\in n$  position

But there exists no subsequence of  $Ix_m$  which is convergent.

(Indeed for  $m \neq n$   $\|Ix_m - Ix_n\| = \sqrt{2} \Rightarrow$  any subsequence of  $Ix_m$   
 cannot be a Cauchy sequence and thus does not converge)

HELLINGER-TOEPLITZ THEOREM

A linear operator on  $H$  is said to be symmetric if  $\forall x, y \in D_T \quad \langle y | Tx \rangle = \langle Ty | x \rangle$

Let us suppose that  $D_T = H \Rightarrow$  one can prove that  $T$  is BOUNDED

SYMMETRIC vs HERMITIAN OPERATORS

We have seen that for  $\dim H < \infty$  SYMMETRIC  $\Leftrightarrow$  HERMITIAN

$\Rightarrow$  let us see that this is not the case when  $\dim H = \infty$

EXAMPLE

$$H = L^2[0,1] \quad A = i \frac{d}{dt} \quad D_A = \{x \in L^2[0,1] \mid \exists x' \in L^2[0,1] \}$$

$$A_0 = i \frac{d}{dt} \quad D_{A_0} = D_A \cap \{x \in L^2[0,1] \mid x(0) = 0, x(1) = 0\}$$

$$\begin{aligned} \langle y | A_0 x \rangle &= \int_0^1 dt y^*(t) i \frac{d}{dt} x(t) = i y^*(t) x(t) \Big|_0^1 + \int_0^1 dt \left( i \frac{d}{dt} y(t) \right)^* x(t) \\ &= \langle A_0 y | x \rangle \end{aligned}$$

$\Rightarrow A_0$  is symmetric      but  $A_0^* = A \neq A_0$ !       $\Rightarrow A_0$  is not hermitian!

Indeed

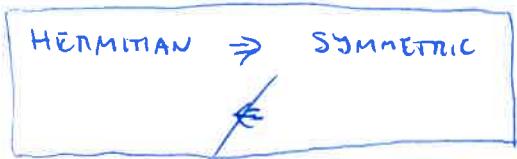
$$\begin{aligned} \langle y | A_0 x \rangle &= i y^*(t) x(t) \Big|_0^1 + \int_0^1 dt \left( i \frac{d}{dt} y(t) \right)^* x(t) = \langle A y | x \rangle \end{aligned}$$

does not need to vanish

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More generally we can say that if  $A$  is symmetric  $\Rightarrow A \subset A^*$  that is

$$A^*|x\rangle = A|x\rangle \quad \forall x \in D_A \quad \text{but } D_{A^*} \supset D_A$$



### FURTHER PROPERTIES

- We have seen that if a linear operator  $T$  is bounded  $\Rightarrow \exists ! T^*$   
One can prove that  $T^*$  is CLOSED
- $T_1$  bounded,  $T_2$  compact  $\Rightarrow \underline{T_2 \cdot T_1 \text{ is compact}}$

Indeed :

$$\begin{array}{ccc} M \text{ bounded} & \xrightarrow{T_1} & M_1 \text{ bounded} & \xrightarrow{T_2} & M_2 \text{ relatively compact} \\ & & & & \\ & & \Rightarrow T_2 \cdot T_1 \text{ is compact!} & & \end{array}$$

T linear operator

$$\text{Resolvent } R_T(\lambda) = (T - \lambda I)^{-1} \quad (\text{if it exists!})$$

$\lambda \in \mathbb{C}$  (or  $H$ ) is a residual point if  $R_T(\lambda)$  exists, and is defined on all  $H$  and bounded

$$p(T) = \{\lambda \mid \lambda \text{ is a residual point}\} \quad \underline{\text{Resolvent set}}$$

$$\sigma(T) = \mathbb{C} - p(T) \quad (\text{if } \mathbb{C} = \mathbb{C} \text{ or } H) \quad \text{is the } \underline{\text{Spectrum of } T}$$

If  $\lambda$  is an eigenvalue of  $T \Rightarrow R_T(\lambda)$  does not exist  $\Rightarrow \lambda \in \sigma(T)$

The set of eigenvalues of  $T$  is called  $\sigma_d(T)$  discrete spectrum

If  $\lambda$  is such that  $R_T(\lambda)$  exists, but it is not bounded, or not defined over all  $H$

$\Rightarrow \lambda \in \sigma_c(T)$  continuous spectrum

$$\sigma(T) = \sigma_d(T) + \sigma_c(T)$$

example

$$H = \mathbb{C}^m \quad \sigma(T) = \sigma_d(T) = \{\lambda_i\} \quad \lambda_i: \text{eigenvalues}$$

$$\sigma_c(T) = \emptyset$$

If  $\lambda$  is not an eigenvalue  $\Rightarrow (T - \lambda I)^{-1}$  exists and its domain is  $H = \mathbb{C}^m$

example

$$H = \ell^2 \quad T_1 : (x_1, x_2, \dots) \rightarrow (0, x_1, x_2, \dots)$$

$$T|x\rangle = \lambda|x\rangle \quad 0 = \lambda x_1 \quad x_1 = \lambda x_2 \quad \dots \quad \Rightarrow x_1 = 0, x_2 = 0, \dots$$

$\Rightarrow T_1$  has no eigenvalues!

$$(T - \lambda)|x\rangle = (-\lambda x_1, x_1 - \lambda x_2, x_2 - \lambda x_3, \dots) \quad (T - \lambda)^{-1}(-\lambda x_1, x_1 - \lambda x_2, \dots) = (x_1, x_2, \dots)$$

$$\text{or } (T - \lambda)^{-1}(y_1, y_2, \dots) = \left( -\frac{y_1}{\lambda}, -\frac{y_2}{\lambda} + \frac{y_1}{\lambda^2}, \dots \right)$$

$\Rightarrow T^{-1}$  does not exist and  $R_T(0)$  does not exist

$$\Rightarrow \lambda = 0 \in \sigma(T)$$

$$\text{actually } \sigma(T) = \{\lambda : |\lambda| \leq 1\}$$

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## SPECTRUM OF COMPACT OPERATORS

We have seen that if  $T$  is a linear compact operator on  $H \Rightarrow$  it is bounded.

$$\Rightarrow \|Tx\| \leq \|T\| \|x\| \quad \Rightarrow \text{if } \lambda \text{ is an eigenvalue } \|Tx\| = |\lambda| \|x\| \quad \Rightarrow |\lambda| \leq \|T\|$$

We conclude that either there is a finite number of eigenvalues, or there must be an accumulation point. We now want to show that  $0 \in \sigma(T)$  if  $\dim H = \infty$ .

Indeed suppose that  $\lambda = 0$  is a regular point for  $T$

$$\Rightarrow T^{-1} \text{ exists, it is bounded and defined over all } H.$$

But the product of a bounded and a compact operator is compact

$$\Rightarrow I = T^{-1}T \text{ is compact} \quad \Rightarrow \text{BUT THIS IS NOT POSSIBLE IF } \dim H = \infty!$$

(see example in  $\ell^2$ )

$$\Rightarrow \text{we must have } 0 \in \sigma(T)$$

We can formulate the following Theorem

### - SPECTRUM OF COMPACT OPERATORS

$T$  compact operator on  $H$ , such that  $\dim H = \infty$

- $0 \in \sigma(T)$
- Each  $\lambda \in \sigma(T)$ ,  $\lambda \neq 0$  is an eigenvalue of  $T$  with finite dimensional eigenspace
- $\sigma(T)$  is either a finite set or a sequence converging to 0

### EXAMPLE

$$H = L^2[0,1] \quad (Tx)(t) = \int_0^t x(s) ds \quad \text{One can show that } T \text{ is } \underline{\text{compact}}$$

$T^{-1}$  is the derivative operator  $\Rightarrow$  not bounded!  $\Rightarrow 0 \in \sigma(T)$

$\forall \lambda \neq 0 \quad (T - \lambda I)^{-1}$  exists and is bounded (solve the equation  $(T - \lambda I)x = y$ )

$\Rightarrow \sigma(T) = \{0\}$  in this case the spectrum is finite!

Let  $T$  be a linear operator on  $H$  with  $T=T^*$  and  $T$  compact. This is the case in which the simple extension of what happens for  $H=\mathbb{C}^n$  holds.

→ We start by showing that  $\|T\| = \sup_{\|x\|=1} |\langle x | Tx \rangle| \equiv \sigma$ . We first prove that  $\|T\| \geq \sigma$ . We have  $|\langle x | Tx \rangle| \leq \|x\| \|Tx\| \leq \|x\| \|T\| \|x\| \Rightarrow \sigma \leq \|T\|$

To show the opposite we define ( $k \in \mathbb{R}$ )

$$|V_+| = k|x\rangle + \frac{1}{n}|Tx\rangle$$

$$|V_-| = k|x\rangle - \frac{1}{n}|Tx\rangle$$

$$\begin{aligned} \text{We have } \|Tx\|^2 &= \frac{1}{4} (\langle TV_+ | V_+ \rangle - \langle TV_- | V_- \rangle) \leq \frac{1}{4} (|\langle TV_+ | V_+ \rangle| + |\langle TV_- | V_- \rangle|) \\ &\leq \frac{\sigma}{4} (\|V_+\|^2 + \|V_-\|^2) = \frac{\sigma}{2} (k^2 \|x\|^2 + \frac{1}{n^2} \|Tx\|^2) \end{aligned}$$

By taking the derivative with respect to  $k^2$  we find that the last expression is minimum when  $k^2 = \frac{\|Tx\|^2}{\|x\|^2}$  and we get

$$\|Tx\|^2 \leq \frac{\sigma}{2} 2 \|Tx\| \|x\| \quad \text{that is } \|Tx\| \leq \sigma \|x\| \Rightarrow \|T\| \leq \sigma$$

→ We now want to show that the eigenvalue with largest modulus is  $|\lambda_1| = \|T\|$

Let  $x_m$  with  $\|x_m\|=1$ ,  $x_m \in H$  |  $|\langle x_m | Tx_m \rangle| \rightarrow \|T\|$  ( $x_m$  exists for the definition of  $\sup$ !)

Since  $T=T^*$   $\langle x_m | Tx_m \rangle$  is real  $\Rightarrow$  this implies  $\langle x_m | Tx_m \rangle \rightarrow \pm \|T\|$

$$\text{We have } \|Tx_m - \lambda_1 x_m\|^2 = \langle Tx_m - \lambda_1 x_m, Tx_m - \lambda_1 x_m \rangle$$

$$= \|Tx_m\|^2 - \lambda_1^2 \langle x_m | Tx_m \rangle - \lambda_1 \langle x_m | Tx_m \rangle + |\lambda_1|^2 \|x_m\|^2$$

$$\text{But since both } \langle Tx_m | x_m \rangle \text{ and } \lambda_1 \text{ are real } \lambda_1 \langle x_m | Tx_m \rangle = |\lambda_1 \langle x_m | Tx_m \rangle|$$

$$= \|Tx_m\|^2 - 2|\lambda_1 \langle x_m | Tx_m \rangle| + |\lambda_1|^2 \leq \|T\|^2 - 2|\lambda_1| |\langle x_m | Tx_m \rangle| + |\lambda_1|^2$$

$$= 2|\lambda_1| (|\lambda_1| - |\langle x_m | Tx_m \rangle|) \rightarrow 0$$

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Since  $X_m$  is bounded and  $T$  is compact  $\Rightarrow \exists$  a convergent subsequence

$T X_m \Rightarrow \lambda_1$  is eigenvalue of  $T$ . Having shown that there exists an eigenvalue  $\lambda_1$  with  $|\lambda_1| = \|T\|$ , we can consider  $H_1 = \text{span of } \{\varphi_i\}$  where  $\varphi_i$  are the eigenvectors of  $\lambda_1$ , and consider  $H_1^\perp$ . We can then focus on  $T^*CT$  where  $T^*$  is the restriction of  $T$  to  $H_1^\perp$ . We have that  $T^*$  is also compact and  $\|T^*\| \leq \|T\|$

$\Rightarrow$  we can repeat the construction done for  $T$  and find  $\lambda_2$  with  $|\lambda_2| \leq |\lambda_1|$

$\Rightarrow$  we can write  $H = H_1 \oplus H_2 + \dots \oplus H_n \oplus \dots \oplus H_0$

$\underbrace{\dim H_i < \infty}_{\text{eigenspace corresponding to } \lambda_i}$

( $\dim H_0 = \infty$  is possible)

$$\Rightarrow T = \sum_{i=1}^{\infty} \lambda_i |\varphi_i\rangle \langle \varphi_i| + (0 \cdot P_0)$$

SPECTRAL  
REPRESENTATION

$$\lambda_i \in \mathbb{R} \quad |\lambda_i| \rightarrow 0$$

$$\sigma(T) = \sigma_d(T) = \{\lambda_i\} \cup \{0\}$$

$U(\phi)$

### EXAMPLE 8)

$$H = \ell^2 \quad x = (x_1, x_2, \dots) \quad T|x\rangle = (x_1, \frac{x_2}{2}, \frac{x_3}{3}, \dots) \quad T = T^* \quad D_T = \ell^2$$

$$\sum_i |x_i|^2 < \infty \quad T \text{ compact}$$

$$\lambda_i = \frac{1}{i} \quad i \in \mathbb{N} \quad \text{corresponds to the}$$

eigenvector

$$|\varphi_i\rangle = (0, 0, \dots, 1, 0, \dots)$$

$\mathbb{C}$  in position

$$T|\varphi_i\rangle = \frac{1}{i} |\varphi_i\rangle$$

$$T = \sum_{i=1}^{\infty} \lambda_i P_i = \sum_{i=1}^{\infty} \frac{1}{i} P_i \quad P_i = |\varphi_i\rangle \langle \varphi_i| \quad H = \bigoplus_{i=1}^{\infty} H_i$$

$\lambda_i \rightarrow 0 \quad 0$  is an accumulation point!

$\dim H_i = 1$

(a) in this case we have  $\sigma(T) = \left\{ \frac{1}{i}, i \in \mathbb{N} \right\} \cup \{0\}$   $\mathcal{E} = \{0\}$

$\lambda=0$  is NOT an eigenvalue but  $T^{-1}$  is not bounded:

and it does not exist over the whole  $H$

(example if  $x_m = \frac{1}{m}$   $\sum |x_m|^2 < \infty$ ,  $\forall x_m \in \ell^2$   
but  $T^{-1}x_m = (1, 1, 1, \dots) \notin \ell^2$ )

THE RESOLVENT

$T$  linear operator on  $H$ . If  $R_T(\lambda)$  exists, bounded, and  $D_{R_T(\lambda)} = H \Rightarrow \lambda$  is an eigenvalue

$$(T - \lambda I) R_T(\lambda) = I_H$$

$$R_T(\lambda) (T - \lambda I) = I_{D_T}$$

$$\Rightarrow R_T(\lambda) T \subseteq T R_T(\lambda) = (T - \lambda I + \lambda I) R_T(\lambda) = I + \lambda R_T(\lambda)$$

Resolvent identity

$$R_T(\lambda_1) = R_1 \quad R_T(\lambda_0) = R_0$$

Let's start from the identity  $(T - \lambda_0 I) - (T - \lambda_1 I) = (\lambda_1 - \lambda_0) I$

- multiply by  $R_0$  on the right  $\rightarrow I - (T - \lambda_1 I) R_0 = (\lambda_1 - \lambda_0) R_0$

- multiply by  $R_1$  on the left  $\rightarrow [R_1 - R_0] = (\lambda_1 - \lambda_0) R_1 R_0$

We can use this equation to find an iterative solution for the resolvent

$$R_1 = R_0 + (\lambda_1 - \lambda_0) R_0 R_0 \quad \text{but if we swap 0 and 1 we get} \quad R_0 = R_1 + (\lambda_0 - \lambda_1) R_0 R_1$$

$$\Rightarrow R_1 = R_0 + (\lambda_1 - \lambda_0) R_0 R_1 \Rightarrow [R_T(\lambda_1), R_T(\lambda_0)] = 0 \quad \text{if } \lambda_1, \lambda_0 \in P(T)$$

$$\begin{aligned} R_1 &= R_0 + (\lambda_1 - \lambda_0) R_0 R_1 = R_0 + (\lambda_1 - \lambda_0) R_0 (R_0 + (\lambda_1 - \lambda_0) R_0 R_1) \\ &= R_0 + (\lambda_1 - \lambda_0) R_0^2 + (\lambda_1 - \lambda_0)^2 R_0^2 R_1 + \dots \end{aligned}$$

$$\Rightarrow R_T(\lambda) = \sum_{m=0}^{\infty} (\lambda - \lambda_0)^m (R_T(\lambda_0))^{m+1} \quad \lambda, \lambda_0 \in P(T)$$

Perturbation theory

$$H = H_0 + V$$

$H_0$  "easy to solve"

$$H\psi = \lambda\psi$$

$\approx$  perturbation (small!)

$$H_0\psi = \lambda_0\psi$$

$$H - \lambda I = H_0 - \lambda I + V$$

$$I = R_H(\lambda) [H_0 - \lambda I + V]$$

$$R_{H_0}(\lambda) = R_H(\lambda) + R_H(\lambda) V R_{H_0}(\lambda)$$

$$R_H(\lambda) = R_{H_0}(\lambda) - R_H(\lambda) \vee R_{H_0}(\lambda)$$

$$\Rightarrow R_H(\lambda) = R_{H_0}(\lambda) \sum_{n=0}^{\infty} (-V R_{H_0}(\lambda))^n$$

Perturbative expansion

### OPERATORS WITH COMPACT RESOLVENT

Suppose that  $T$  is a linear operator on  $H$  and that  $R_0 \equiv R_T(\lambda_0) = (T - \lambda_0 I)^{-1}$

$\hookrightarrow$  compact for  $\lambda \in p(T)$ . This implies that  $R_0$  is bounded and defined overall  $H \Rightarrow$  We can show that  $\forall \lambda \in p(T)$   $R_T(\lambda)$  is also compact

Use the resolvent identity:  $R_T(\lambda) - R_T(\lambda_0) = (\lambda - \lambda_0) R_T(\lambda) R_T(\lambda_0)$

$$R_T(\lambda) = [1 + (\lambda - \lambda_0) R_T(\lambda)] R_T(\lambda_0) \Rightarrow \text{the product is compact}$$

$\hookrightarrow$  bounded       $\hookrightarrow$  compact

From the spectral theorem for compact operators we know that  $R_T(\lambda)$  has a discrete spectrum, with possibly 0 as accumulation point  $\sigma(R_T(\lambda)) = \sigma_d(R_T(\lambda))$

CAN WE SAY SOMETHING ON THE SPECTRUM OF  $T$ ?

Let us consider  $Q \equiv -\lambda R_0 (R_0 - \lambda I)^{-1}$  bounded for  $\lambda \in p(R_0)$  and defined overall  $H$

$$Q(R_0 - \lambda I) = -\lambda R_0 \Rightarrow \lambda(Q - R_0) = Q R_0 \Rightarrow Q - R_0 = \frac{1}{\lambda} Q R_0 \quad \lambda \neq 0$$

But this is the equation fulfilled by  $R_T(\lambda_0 + \frac{1}{\lambda})$ !  $\star$

$$\Rightarrow Q = -\lambda R_0 (R_0 - \lambda I)^{-1} = R_T(\lambda_0 + \frac{1}{\lambda}) \quad \text{bounded and defined all over } H$$

$\text{if } \lambda \neq 0 \quad \lambda \in p(R_0)$

$\Rightarrow$

$$\lambda_0 + \frac{1}{\lambda} \in p(T) \Leftrightarrow \lambda \in p(R_0), \lambda \neq 0$$

$\Rightarrow \sigma(T)$  includes  $\lambda_0 + \frac{1}{\lambda_m}$  and possibly the accumulation point or  $\infty$  ( $\lim \lambda_m \rightarrow 0$ )

$\hookrightarrow$  eigenvalues of  $R_0 \equiv R_T(\lambda_0)$

### EXAMPLE : STURM-LIOUVILLE OPERATOR

Differential operator  $L = -\frac{d}{dx} \left( p(x) \frac{d}{dx} \right) + q(x)$  defined over  $L^2[-\infty]$

$L = L^*$ ,  $L$  not bounded, but has compact resolvent

$\Rightarrow$  distinct eigenvalues with  $\infty$  as accumulation point

$L(x) = \lambda |x|$  differential equation  $\Rightarrow$  prototype of familiar differential equations!

#### example

$$H = L^2[-1,1]$$

$$p(x) = 1-x^2$$

$$q(x) = 0$$

$$Ly = \lambda y$$

$$\lambda = l(l+1) \quad \Rightarrow \text{Legendre equation}$$

$$(1-x^2)y'' - 2xy' + l(l+1)y = 0$$

$\Rightarrow$  eigenfunctions of  $L$  are in this case the familiar Legendre Polynomials!

(basis for  $L^2[-1,1]$ )

$$p = e^{-x^2}, q = 0 \quad \text{weight } e^{-x^2}$$

Analogously we can treat the case of Legendre and Hermite polynomials.

$$\begin{cases} l=0 \rightarrow 1 \\ l=1 \rightarrow x \\ l=2 \rightarrow 3x^2 - \dots \end{cases}$$

### SPECTRAL FAMILY AND RESOLUTION OF THE IDENTITY

Goal: extend the spectral representation to hermitian but not necessarily compact operators

#### Absolute definition

A family of orthogonal projectors  $E(\lambda)$ ,  $-\infty < \lambda < \infty$  in the Hilbert space  $H$

is called a RESOLUTION OF THE IDENTITY (a spectral family) if it satisfies the following conditions

- $E(\lambda) E(\mu) = E(\min(\lambda, \mu))$

- $E(-\infty) = 0 \quad E(+\infty) = I$

- $\lim_{\epsilon \rightarrow 0^+} E(\lambda + \epsilon) = E(\lambda)$

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Let us go back to the case in which  $T$  is compact

$$\Rightarrow \sigma(T) = \sigma_d(T), \quad \sigma_c(T) = \emptyset \quad T = \sum_i \lambda_i P_i$$

$\cup \{0\}$       on  $\{0\}$

$P_i$  projectors on the eigenspace corresponding to the eigenvalue  $\lambda_i$

Let us define  $E(\lambda) = \sum_{\lambda_i \leq \lambda} P_i$  operator valued function of  $\lambda$

More explicitly, suppose  $m_1 = \min(\lambda_i)$ ,  $m_2 = \max(\lambda_i)$

$$\Rightarrow E(\lambda) = 0 \quad \lambda < m_1; \quad E(\lambda) = I \quad \lambda > m_2$$

moreover  $E^2(\lambda) = E(\lambda)$  and  $E^*(\lambda) = E(\lambda)$

We also have for  $\lambda \leq m$   $E(\lambda)E(m) = E(m)E(\lambda) = E(\lambda)$

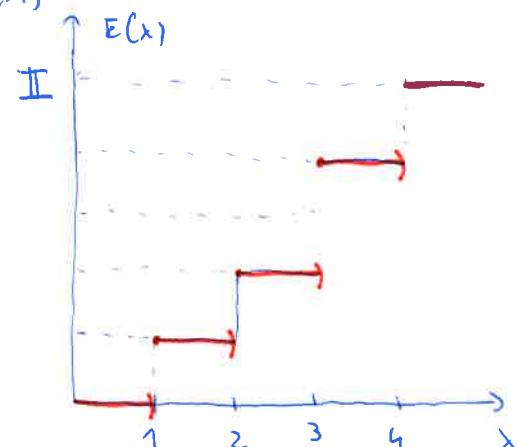
example

$$\lambda_1 = 1 \quad \lambda_2 = 2$$

$$\lambda_3 = 3 \quad \lambda_4 = 4$$

$$T = \sum_{i=1}^4 \lambda_i P_i \quad m(\lambda_3) = 2$$

$\circlearrowleft$  multiplicity



Now consider the case in which the  $\lambda_i$  become

closer and closer  $\Delta E_i = E(\lambda_i) - E(\lambda_{i-1}) = P_i$

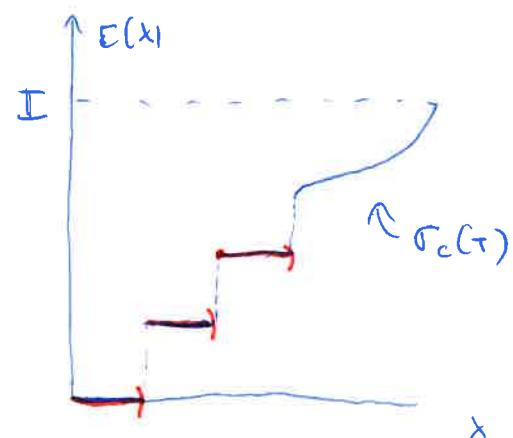
$$T = \sum_i \lambda_i P_i = \sum_i \lambda_i \Delta E_i \rightarrow \int_{-\infty}^{+\infty} \lambda dE(\lambda)$$

the sum becomes an integral

In the case of a generic (not necessarily compact or with compact resolvent) hermitian

operator  $T$ , we have  $\sigma_c(T) \neq \emptyset$   $\sigma(T) \subset \mathbb{R}$

$\Rightarrow$  the function  $E(\lambda)$  is not anymore step function!



SPECTRAL THEOREM FOR GENERIC HERMITIAN LINEAR OPERATORS:

$\Rightarrow T$  hermitian operator on  $H \Rightarrow \exists E(\lambda)$  spectral family |  $T = \int_{\mathbb{R}} \lambda dE(\lambda)$

The real axis is divided as follows:

- $\lambda_0 \in P(T)$  if  $E(\lambda)$  is constant around  $\lambda_0$
- $\lambda_0 \in \sigma_d(T)$  if  $E(\lambda)$  has a step in  $\lambda_0$
- $\lambda_0 \in \sigma_c(T)$  if  $E(\lambda)$  is continuous in  $\lambda_0$  (but not constant)

EXAMPLE

$$H = L^2[0,1] \quad \text{multiplication operator} \quad T|\psi\rangle = x|\psi\rangle$$

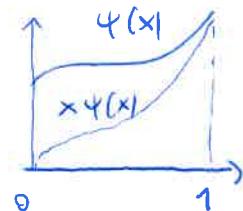
$$E(\lambda)|\psi\rangle = \begin{cases} \psi(x) & x \leq \lambda \\ 0 & x > \lambda \end{cases} = \Theta(\lambda - x)\psi(x)$$

$E(\lambda)$  has no step  
 $\Rightarrow$  no eigenvalue

Equivalently, suppose  $\lambda$  is an eigenvalue and  $\psi_\lambda$  the corresponding eigenvector

$$T|\psi_\lambda\rangle = \lambda|\psi_\lambda\rangle$$

$$x\psi_\lambda(x) = \lambda\psi_\lambda(x)$$



$\Rightarrow$  they cannot be proportional!

$\Rightarrow T$  has no eigenvalue

Actually it is possible to define eigenvectors by considering  $\psi(x)$  localized in point

$$\psi(x) \sim \delta(x-\lambda) \Rightarrow T\psi(x) = \lambda\delta(x-\lambda)$$

but  $\delta(x-\lambda) \notin L^2[0,1]$  it is a distribution!

$$\Rightarrow \lambda \in [0,1] \quad \lambda \in \sigma_c(T)$$

A physical system has a state which is described as an element of a Hilbert space  $H$

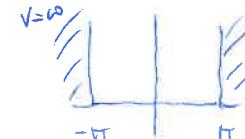
$$|\psi\rangle \in H \quad \|\psi\|=1$$

example

- Spin  $\frac{1}{2}$  particle  $H = \mathbb{C}^2 \quad |\psi\rangle = \begin{pmatrix} a \\ b \end{pmatrix} \in \mathbb{C}^2 \quad |a|^2 + |b|^2 = 1$

- particle in 1 dimension  $H = L^2(-\infty, \infty) \quad \psi(x) \quad$  WAVE FUNCTION

- particle in a potential well  $H = L^2[-\pi, \pi] \quad \psi(x)$



Observables are described as Hermitian operators ( $\hat{O}$ ) (you can measure them simultaneously only if they commute:  $[\hat{X}, \hat{P}_X] = i\hbar$ )

- 2 components of  $\frac{1}{2}$  spin  $\hat{S}_z = \frac{1}{2} \sigma_z = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} \end{pmatrix} \quad \hat{S}_z^+ = \hat{S}_z$

$$\hat{S}_x = \frac{1}{2} \sigma_x$$

- Position operator  $\hat{x}|\psi\rangle = x|\psi\rangle$

$$\{\sigma_i, \sigma_j\} = 2\delta_{ij}$$

- Momentum operator  $\hat{p}|\psi\rangle = -i\hbar \frac{\partial}{\partial x} \psi(x)$

$$\Rightarrow \frac{1}{h} (\sigma_x^2 + \sigma_y^2 + \sigma_z^2) = \frac{3}{4} I$$

If the system is in the state  $|\psi\rangle$  and a measurement is done of the observable  $\hat{O}$

$\Rightarrow$  the expectation value of the observable is

$$\langle \psi | \hat{O} | \psi \rangle = \langle \psi | \sum_i \lambda_i P_i | \psi \rangle = \sum_i \lambda_i \langle \psi | P_i | \psi \rangle$$

if  $\sigma(O) = \sigma_d(O)$

$$\stackrel{''}{w}(\lambda_i)$$

$$\sum_i w(\lambda_i) = \sum_i \langle \psi | P_i | \psi \rangle = \langle \psi | \mathbb{I} | \psi \rangle = \|\psi\|^2 = 1$$

- If the spectrum of  $\hat{O}$  is a pure discrete spectrum we will always get an eigenvalue
- We cannot say which one, but only its probability!
- If  $\hat{O}|\psi\rangle = \lambda_i|\psi\rangle \Rightarrow w(\lambda_i) = 1$  and  $w(\lambda_j) = 0$  if  $i \neq j$

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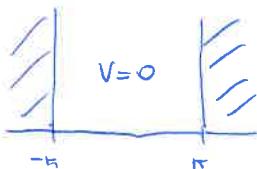
example  $S_z = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} \end{pmatrix}$   $|4\rangle = \begin{pmatrix} a \\ b \end{pmatrix}$   $P_{Y_1} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$   $P_{-Y_1} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

$w(Y_1) = \langle 4 | P_{Y_1} | 4 \rangle = |a|^2$

$w(-Y_1) = \langle 4 | P_{-Y_1} | 4 \rangle = |b|^2$

$\langle 4 | S_z | 4 \rangle = \frac{1}{2} |a|^2 - \frac{1}{2} |b|^2$

expectation value of a measurement  
of  $S_z$

example

$\Psi_m = \frac{1}{\sqrt{2\pi}} e^{imx} \quad m \in \mathbb{N}$

$\langle \psi_n | \psi_m \rangle = \delta_{nm}$

$P(\psi_m) = -i\hbar \frac{\partial}{\partial x} \psi_m = -i\hbar \frac{1}{\sqrt{2\pi}} im e^{imx} = m\hbar |\psi_m\rangle$

- $P$  is not bounded but it has a compact resolvent  $\Rightarrow \sigma(P) = \sigma_d(P) = \{\tilde{\mu}_m, m \in \mathbb{N}\}$

$\langle \psi | \hat{P} | \psi \rangle = \int_{-\pi}^{\pi} \psi^*(x) (-i\hbar \frac{d}{dx}) \psi(x) dx = \sum m n w(m)$

$\hat{P} = \sum_{m \in \mathbb{N}} m n |\psi_m\rangle \langle \psi_m|$ 

C projections

$w(n) = \langle \psi | P_n | \psi \rangle = |\langle \psi | \psi_n \rangle|^2$

$\left| \int_{-\pi}^{\pi} \frac{1}{\sqrt{2\pi}} e^{-inx} \psi(x) dx \right|^2$

- $\hat{X}$  position operator  $\nexists$  eigenvectors, pure continuous spectrum  $\sigma(X) = \sigma_c(X)$

bounded, but not compact, and no compact resolvent

$= [-\pi, \pi]$